A knot is the image of an embedding of circle in the 3-sphere  $S^3$ , denoted by K. A link is the image of an embedding of circles  $S^1 \cup S^1 \cup \cdots \cup S^1$  in the 3-sphere  $S^3$ . Let  $L = K_1 \cup K_2 \cup \cdots \cup K_n$  be an n-component link in  $S^3$ , and N(L) a tubular neighborhood of L, and E(L) the exterior of L. Let  $\chi(L,0)$  be the 3-manifold obtained from E(L) by attaching n solid tori  $V_1, V_2, \ldots, V_n$  to  $\partial E(L)$  such that the meridian of  $\partial V_i$  is mapped to the longitude of  $K_i$  ( $i = 1, 2, \ldots, n$ ). We call  $\chi(L,0)$  the 3-manifold obtained by the 0-surgery of  $S^3$  along L. It is well known that every closed connected orientable 3-manifold is obtained by the 0-surgery of  $S^3$  along a link.

Let M be a closed connected orientable 3-manifold. For any M, there exist handlebodies  $H_1$  and  $H_2$  of same genus and a homeomorphism  $f: \partial H_1 \to \partial H_2$  such that  $M = H_1 \cup_f H_2$ . We call the triple  $(H_1, H_2; f)$  a Heegaard splitting of M and we call  $f(\partial H_1) = \partial H_2$  the Heegaard surface. The Heegaard genus of M is the minimal genus of Heegaard surfaces, denoted by  $g_H(M)$ .

Let bridge(L) (resp. braid(L)) be the bridge index (resp. the braid index) (cf. [5]). The bridge genus  $g_{bridge}(M)$  (resp. the braid genus  $g_{braid}(M)$ ) of M is the minimal number of bridge(L) (resp. braid(L)) for any L such that M is obtained by the 0-surgery of  $S^3$  along L. The bridge genus and the braid genus are introduced by A.Kawauchi [6].

I show the following results and my paper On Heegaard genus, bridge genus and braid genus for a 3-manifold is published in Journal of Knot Theory and Its Ramifications.

$$g_{\mathrm{H}}(M) \leq g_{\mathrm{bridge}}(M) \leq g_{\mathrm{braid}}(M).$$

Next, I calculate the bridge genus and the braid genus for lens space L(p,q) as follows. For every even integer n,

$$g_{\mathrm{bridge}}(L(n,1)) = g_{\mathrm{braid}}(L(n,1)) = 3.$$

For every odd integers n, m,

$$g_{\mathrm{bridge}}(L(nm-1,m)) = g_{\mathrm{braid}}(L(nm-1,m)) = 4.$$

For lens space L(8,3),

$$4 \le g_{\text{bridge}}(L(8,3)) = g_{\text{braid}}(L(8,3)) \le 5.$$