

## My future research plan

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My research subjects are Teichmüller spaces and mapping class groups. The mapping class group is an important research subject in many fields such as topology, hyperbolic geometry, theory of low-dimensional manifolds, combinatorial group theory, dynamical systems and complex analysis. The study of the mapping class group produced the beautiful Nielsen-Thurston theory and has spurred the advance of mathematics in the 21st century. We obtain a deep insight of the mapping class group when it is paired with an action on some geometrical objects. One of them is the Teichmüller space, a deformation space of Riemann surfaces on which the mapping class group acts as the group of holomorphic automorphisms. The mapping class group is also called the Teichmüller modular group.

A Teichmüller space admits several coordinate systems. Coordinate system induced by holomorphic quadratic differentials on a Riemann surface employed by Teichmüller and Bers, and Fenchel-Nielsen coordinates based on hyperbolic geometry are among them. Let  $S$  be an orientable surface of genus  $g$  with boundary curves  $C_1, \dots, C_m$  and  $\mathcal{T}_{g,m}(L_1, \dots, L_m)$  the Teichmüller space of hyperbolic structures on  $S$  with  $C_k$  totally geodesic of length  $L_k$ . Lengths of suitably chosen  $d + 1$  closed geodesic curves embed  $\mathcal{T}_{g,m}(L_1, \dots, L_m)$  into  $\mathbb{R}^{d+1}$ , where  $d = 6g - 4 + 3m$  is the dimension of Teichmüller space (P. Schmutz et al.) (It is known that no tuple of lengths of  $d$  closed geodesic curves can embed the Teichmüller space into  $\mathbb{R}^d$ .) I am interested in how a mapping class is described in terms of geodesic length parameters and proved that it is a rational transformation in the parameter space. This enables us to treat the mapping class group and the Teichmüller space and also related subjects in 3-dimensional manifolds, dynamical systems and number theory in quantitative and computational methods. My research plan is to tackle the following problems to find

- (1) A fundamental region for the action of mapping class group and also the moduli space.
- (2) Methods to calculate the Weil-Petersson volume of a moduli space.
- (3) Integer solutions of Diophantine equations analogous to that of the Markoff equation.
- (4) Group representations of the mapping class group.
- (5) Action of the mapping class group on the  $SL(2, \mathbb{C})$ -representation space of  $\pi_1(S)$ .
- (6) Examples of hyperbolic 3-manifolds which fiber over the circle.

We have tried to apply the rational representation of the mapping class group to find Kleinian groups and hyperbolic 3-manifolds derived from the dynamics of the mapping classes but not have been successful so far, due to the difficulty to determine discreteness of a subgroup of  $SL(2, \mathbb{C})$ . Therefore our research plan is to find effective computational methods for discreteness criterion for subgroups of  $SL(2, \mathbb{C})$  and then make full use of our rational representation of the mapping class group to find many examples of Kleinian groups and then hyperbolic 3-manifolds which fiber over the circle. Our research is supported by JSPS KAKENHI Grant in Aid for Scientific Research (C) for the period 2024-2026.