EHRHART POLYNOMIALS OF 3-DIMENSIONAL SIMPLE INTEGRAL CONVEX POLYTOPES

YUSUKE SUYAMA

ABSTRACT. We give an explicit formula on the Ehrhart polynomial of a 3dimensional simple integral convex polytope by using toric geometry.

1. INTRODUCTION

Let $P \subset \mathbb{R}^d$ be an integral convex polytope of dimension d, that is, a convex polytope whose vertices have integer coordinates. For a non-negative integer l, we write $lP = \{lx \mid x \in P\}$. Ehrhart [2] proved that the number of lattice points in lP can be expressed by a polynomial in l of degree d:

$$|(lP) \cap \mathbb{Z}^d| = c_d l^d + c_{d-1} l^{d-1} + \dots + c_0.$$

This polynomial is called the *Ehrhart polynomial* of P. It is known that:

- (1) $c_0 = 1$.
- (2) c_{d-1} is half of the sum of relative volumes of facets of P([1, Theorem 5.6]).
- (3) c_d is the volume of P ([1, Corollary 3.20]).

However, we have no formula on other coefficients of Ehrhart polynomials. In particular, we do not know a formula on c_1 for a general 3-dimensional integral convex polytope. In this paper, we find an explicit formula on c_1 of the Ehrhart polynomial of a 3-dimensional *simple* integral convex polytope, see Theorem 5.

Pommersheim [4] gave a method for computing the (d-2)-nd coefficient of the Ehrhart polynomial of a *d*-dimensional simple integral convex polytope *P* by using toric geometry. He obtained an explicit description of the Ehrhart polynomial of a tetrahedron by using this method. Our formula is obtained by using this method for a general 3-dimensional simple integral convex polytope.

The structure of the paper is as follows. In Section 2, we state the main theorem and give a few examples. In Section 3, we give a proof of the main theorem.

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2. The main theorem

Let $P \subset \mathbb{R}^3$ be a 3-dimensional simple integral convex polytope, and let F_1, \ldots, F_n be the facets of P. For $k = 1, \ldots, n$, we denote by $v_k \in \mathbb{Z}^3$ the inward-pointing primitive normal vector of F_k . For an edge E of P, we denote by Vol(E) the relative

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volume of E, that is, the length of E measured with respect to the lattice of rank one in the line containing E.

DEFINITION 1. For each edge $E = F_{k_1} \cap F_{k_2}$ of P, we define an integer m(E) and a rational number s(E) as follows:

- (1) We define $m(E) = |((\mathbb{R}v_{k_1} + \mathbb{R}v_{k_2}) \cap \mathbb{Z}^3)/(\mathbb{Z}v_{k_1} + \mathbb{Z}v_{k_2})|.$
- (2) There exists a basis e_1, e_2 for $(\mathbb{R}v_{k_1} + \mathbb{R}v_{k_2}) \cap \mathbb{Z}^3$ such that $v_{k_1} = e_1$ and $v_{k_2} = pe_1 + qe_2$ for some $q > p \ge 0$. Then we define s(E) = s(p,q), where s(p,q) is the Dedekind sum, which is defined by

$$s(p,q) = \sum_{i=1}^{q} \left(\left(\frac{i}{q}\right) \right) \left(\left(\frac{pi}{q}\right) \right), \quad ((x)) = \begin{cases} x - [x] - \frac{1}{2} & (x \notin \mathbb{Z}), \\ 0 & (x \in \mathbb{Z}). \end{cases}$$

REMARK 2. We have q = m(E). Although p is not uniquely determined, s(p,q) does not depend on the choice of e_1, e_2 . Thus s(E) is well-defined.

DEFINITION 3. For each facet F of P, we define a rational number C(F) as follows. We name vertices and facets around F as in Figure 1. We denote by $v \in \mathbb{Z}^3$ the inward-pointing primitive normal vector of F.

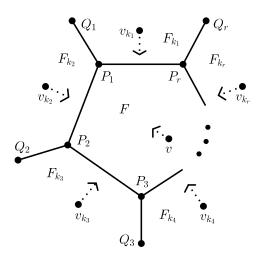


FIGURE 1. vertices and facets around F.

For $i = 1, \ldots, r$, we define

$$\varepsilon_{i} = \det(v, v_{k_{i+1}}, v_{k_{i}}) > 0, \quad a_{i} = \frac{\langle \overrightarrow{P_{i-1}Q_{i-1}}, v_{k_{i+1}} \rangle}{\varepsilon_{i} \langle \overrightarrow{P_{i-1}Q_{i-1}}, v \rangle}, \quad b_{i} = \frac{\langle \overrightarrow{P_{i}P_{i+1}}, v_{k_{i-1}} \rangle}{\varepsilon_{i-1} \langle \overrightarrow{P_{i}P_{i+1}}, v_{k_{i}} \rangle},$$

where $v_{k_0} = v_{k_r}, v_{k_{r+1}} = v_{k_1}, \varepsilon_0 = \varepsilon_r, P_0 = P_r, P_{r+1} = P_1, Q_0 = Q_r$ and $\langle \cdot, \cdot \rangle$ is the standard inner product on \mathbb{R}^3 . Then we define

$$C(F) = -\sum_{2 \le i < j \le r} a_i \begin{vmatrix} b_{i+1} & \varepsilon_{i+1}^{-1} & 0 & \cdots & 0 \\ \varepsilon_{i+1}^{-1} & b_{i+2} & \varepsilon_{i+2}^{-1} & \ddots & \vdots \\ 0 & \varepsilon_{i+2}^{-1} & \ddots & \ddots & 0 \\ \vdots & \ddots & \ddots & b_{j-2} & \varepsilon_{j-2}^{-1} \\ 0 & \cdots & 0 & \varepsilon_{j-2}^{-1} & b_{j-1} \end{vmatrix} \varepsilon_i \varepsilon_{i+1} \cdots \varepsilon_{j-1} \frac{\operatorname{Vol}(P_{j-1}P_j)}{m(P_{j-1}P_j)},$$

where $P_{j-1}P_j$ is the edge whose endpoints are P_{j-1} and P_j , and the determinants above are understood to be one when j = i + 1.

REMARK 4. The proof of Theorem 5 below shows that C(F) does not depend on the choice of F_{k_1} .

The following is our main theorem:

Theorem 5. Let $P \subset \mathbb{R}^3$ be a 3-dimensional simple integral convex polytope, and let E_1, \ldots, E_m and F_1, \ldots, F_n be the edges and the facets of P, respectively. Then the coefficient c_1 of the Ehrhart polynomial $|(lP) \cap \mathbb{Z}^3| = c_3l^3 + c_2l^2 + c_1l + c_0$ is given by

$$\sum_{j=1}^{m} \left(s(E_j) + \frac{1}{4} \right) \operatorname{Vol}(E_j) + \frac{1}{12} \sum_{k=1}^{n} C(F_k).$$

EXAMPLE 6. Let a, b, c be positive integers with gcd(a, b, c) = 1 and let $P \subset \mathbb{R}^3$ be the tetrahedron with vertices

$$O = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \quad P_1 = \begin{pmatrix} a \\ 0 \\ 0 \end{pmatrix}, \quad P_2 = \begin{pmatrix} 0 \\ b \\ 0 \end{pmatrix}, \quad P_3 = \begin{pmatrix} 0 \\ 0 \\ c \end{pmatrix}.$$

We put A = gcd(b, c), B = gcd(a, c), C = gcd(a, b) and d = ABC. Then we have the following table:

е	edge E	ge $E \mid OP_1 \mid OP_2 \mid OP_3 \mid$		P_1P_2		$P_{1}P_{3}$		P_2P_3		
I	$\operatorname{Vol}(E)$	a	b	c	C		В		A	
	m(E)	1	1	1	cC/d		bB/d		aA/d	
	s(E)	0	0	0	$-s\left(\frac{ab}{d},\frac{cC}{d}\right)$		-s	$\left(\frac{ac}{d}, \frac{bB}{d}\right)$	$-s\left(\frac{bc}{d},\frac{aA}{d}\right)$	
	facet F				OP_1P_2	OP_1	P_3	OP_2P_3	$P_1P_2P_3$	
	inward-pointing primitive normal vector of F C(F)				$\left(\begin{array}{c}0\\0\\1\end{array}\right)$	$ \left(\begin{array}{c} 0\\ 1\\ 0 \end{array}\right) $		$\left(\begin{array}{c}1\\0\\0\end{array}\right)$	$\left(egin{array}{c} -bc/d \ -ac/d \ -ab/d \end{array} ight)$	
					ab/c ac		/b	bc/a	$d^2/(abc)$	

TABLE 1. the values of Vol(E), s(E) and C(F).

Thus we have

$$\sum_{E:\text{edge}} \left(s(E) + \frac{1}{4} \right) \operatorname{Vol}(E) + \frac{1}{12} \sum_{F:\text{facet}} C(F)$$

$$= \frac{a}{4} + \frac{b}{4} + \frac{c}{4} + \left(-s \left(\frac{ab}{d}, \frac{cC}{d} \right) + \frac{1}{4} \right) C + \left(-s \left(\frac{ac}{d}, \frac{bB}{d} \right) + \frac{1}{4} \right) B$$

$$+ \left(-s \left(\frac{bc}{d}, \frac{aA}{d} \right) + \frac{1}{4} \right) A + \frac{1}{12} \left(\frac{ab}{c} + \frac{ac}{b} + \frac{bc}{a} + \frac{d^2}{abc} \right),$$

which coincides with the formula in [4, Theorem 5].

EXAMPLE 7. Let a and c be positive integers and b be a non-negative integer. Consider the convex hull $P \subset \mathbb{R}^3$ of the six points

$$O = \begin{pmatrix} 0\\0\\0 \end{pmatrix}, \quad A = \begin{pmatrix} a\\0\\0 \end{pmatrix}, \quad B = \begin{pmatrix} 0\\a\\0 \end{pmatrix},$$
$$O' = \begin{pmatrix} b\\0\\c \end{pmatrix}, \quad A' = \begin{pmatrix} a+b\\0\\c \end{pmatrix}, \quad B' = \begin{pmatrix} b\\a\\c \end{pmatrix}.$$

P is a 3-dimensional simple polytope. We put $g=\gcd(b,c).$ Then we have the following table:

edge E	OA	OB	AB	OO'	AA'	BB'	O'A'	O'B'	A'B'	
$\operatorname{Vol}(E)$	a	a	a	g	g	g	a	a	a	
m(E)	1	c/g	c/g	1	1	c/g	1	c/g	c/g	
s(E)	0	$-s\left(\frac{b}{g},\frac{c}{g}\right)$	$s\left(\frac{b}{g},\frac{c}{g}\right)$	0	0	$-s\left(1,\frac{c}{g}\right)$	0	$s\left(\frac{b}{g},\frac{a}{g}\right)$	$\left \frac{b}{g} \right - s\left(\frac{b}{g}, \frac{c}{g}\right)$	
	$\begin{tabular}{ c c c c c }\hline facet F \\ \hline inward-pointing primitive \\ normal vector of F \\ \hline \end{tabular}$			OAA'O'		OBB'O'	ABB'A'		O'A'B'	
				$\left(\begin{array}{c}0\\1\\0\end{array}\right)$		$\left(\begin{array}{c} c/g \\ 0 \\ -b/g \end{array}\right)$	$\left(\begin{array}{c} -c/g\\ -c/g\\ b/g\end{array}\right)$		$\left(\begin{array}{c}0\\0\\-1\end{array}\right)$	
	C((F)	0	0		g^2/c	g^2/c		0	
TABLE 2. the configuration of $V_{-1}(E) = (E)$ and $C(E)$										

TABLE 2. the values of Vol(E), s(E) and C(F).

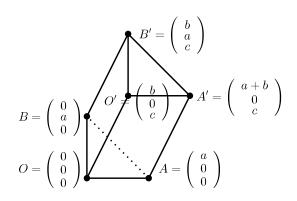


FIGURE 2. the simple polytope P.

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Thus we have

$$\begin{split} &\sum_{E:\text{edge}} \left(s(E) + \frac{1}{4} \right) \text{Vol}(E) + \frac{1}{12} \sum_{F:\text{facet}} C(F) \\ &= -s \left(1, \frac{c}{g} \right) g + \frac{3a}{2} + \frac{3g}{4} + \frac{1}{12} \left(c + \frac{2g^2}{c} \right) \\ &= -g \sum_{i=1}^{c/g-1} \left(\frac{i}{\frac{c}{g}} - \frac{1}{2} \right)^2 + \frac{3a}{2} + \frac{3g}{4} + \frac{c}{12} + \frac{g^2}{6c} \\ &= -g \sum_{i=1}^{c/g-1} \left(\frac{g^2}{c^2} i^2 - \frac{g}{c} i + \frac{1}{4} \right) + \frac{3a}{2} + \frac{3g}{4} + \frac{c}{12} + \frac{g^2}{6c} \\ &= -\frac{g^3}{c^2} \frac{\left(\frac{c}{g} - 1 \right) \frac{c}{g} \left(\frac{2c}{g} - 1 \right)}{6} + \frac{g^2}{c} \frac{\left(\frac{c}{g} - 1 \right) \frac{c}{g}}{2} - g \frac{\frac{c}{g} - 1}{4} + \frac{3a}{2} + \frac{3g}{4} + \frac{c}{12} + \frac{g^2}{6c} \\ &= \frac{3a}{2} + g. \end{split}$$

On the other hand, since

$$\#\{(x,y)\in\mathbb{Z}^2\mid (x,y,z)\in lP\} = \begin{cases} \frac{(al+1)(al+2)}{2} & ((c/g)|z), \\ \frac{al(al+1)}{2} & ((c/g)\not|z) \end{cases}$$

for $z = 0, 1, \ldots, cl$, we have

$$\begin{split} |(lP) \cap \mathbb{Z}^3| &= \frac{(al+1)(al+2)}{2}(gl+1) + \frac{al(al+1)}{2}((cl+1) - (gl+1)) \\ &= \frac{a^2c}{2}l^3 + \frac{1}{2}\left(a^2 + ac + 2ag\right)l^2 + \left(\frac{3a}{2} + g\right)l + 1. \end{split}$$

The coefficient of l is also 3a/2 + g.

3. Proof of Theorem 5

First we recall some facts about toric geometry, see [3] for details. Let $P \subset \mathbb{R}^d$ be a *d*-dimensional integral convex polytope. We define a cone

$$\sigma_F = \{ v \in \mathbb{R}^d \mid \langle u' - u, v \rangle \ge 0 \ \forall u' \in P, \forall u \in F \}$$

for each face F of P. Then the set

$$\Delta_P = \{ \sigma_F \mid F \text{ is a face of } P \}$$

of such cones forms a fan in \mathbb{R}^d , which is called the *normal fan* of P. Let $X(\Delta_P)$ be the associated projective toric variety. We denote by $V(\sigma)$ the subvariety of $X(\Delta_P)$ corresponding to $\sigma \in \Delta_P$. Let $\mathrm{Td}_i(X(\Delta_P)) \in A_i(X(\Delta_P))_{\mathbb{Q}}$ be the *i*-th Todd class in the Chow group of *i*-cycles with rational coefficients.

Theorem 8. Let $P \subset \mathbb{R}^d$ be a d-dimensional integral convex polytope and $|(lP) \cap \mathbb{Z}^d| = c_d l^d + c_{d-1} l^{d-1} + \dots + c_0$ be its Ehrhart polynomial. If $\mathrm{Td}_i(X(\Delta_P))$ has an expression of the form $\sum_F r_F[V(\sigma_F)]$ with $r_F \in \mathbb{Q}$, then we have $c_i = \sum_F r_F \mathrm{Vol}(F)$, where $[V(\sigma_F)]$ is the class of $V(\sigma_F)$ in the Chow group and $\mathrm{Vol}(F)$ is the relative volume of F.

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Now we assume that d = 3 and P is simple. Then the associated toric variety $X(\Delta_P)$ is \mathbb{Q} -factorial and we know the ring structure of the Chow ring $A^*(X(\Delta_P))_{\mathbb{Q}}$ with rational coefficients. Let E_1, \ldots, E_m and F_1, \ldots, F_n be the edges and the facets of P, respectively. We have

(3.1)
$$\sum_{k=1}^{n} \langle u, v_k \rangle [V(\sigma_{F_k})] = 0 \quad \forall u \in (\mathbb{Q}^3)^*.$$

If F_{k_1} and F_{k_2} are distinct, then

(3.2)
$$[V(\sigma_{F_{k_1}})][V(\sigma_{F_{k_2}})] = \begin{cases} \frac{1}{m(E_j)}[V(\sigma_{E_j})] & (1 \le \exists j \le m : F_{k_1} \cap F_{k_2} = E_j), \\ 0 & (F_{k_1} \cap F_{k_2} = \emptyset) \end{cases}$$

in $A^*(X(\Delta_P))_{\mathbb{Q}}$.

Pommersheim gave an expression of $\operatorname{Td}_{d-2}(X(\Delta_P))$ for a *d*-dimensional simple integral convex polytope $P \subset \mathbb{R}^d$. In the case where d = 3, we have the following:

Theorem 9 (Pommersheim [4]). If $P \subset \mathbb{R}^3$ is a 3-dimensional simple integral convex polytope, then

$$\mathrm{Td}_1(X(\Delta_P)) = \sum_{j=1}^m \left(s(E_j) + \frac{1}{4} \right) [V(\sigma_{E_j})] + \frac{1}{12} \sum_{k=1}^n [V(\sigma_{F_k})]^2.$$

We use the notation in Definition 3. It suffices to show

$$[V(\sigma_F)]^2 = -\sum_{2 \le i < j \le r} a_i \begin{vmatrix} b_{i+1} & \varepsilon_{i+1}^{-1} & 0 & \cdots & 0 \\ \varepsilon_{i+1}^{-1} & b_{i+2} & \varepsilon_{i+2}^{-1} & \ddots & \vdots \\ 0 & \varepsilon_{i+2}^{-1} & \ddots & \ddots & 0 \\ \vdots & \ddots & \ddots & b_{j-2} & \varepsilon_{j-2}^{-1} \\ 0 & \cdots & 0 & \varepsilon_{j-2}^{-1} & b_{j-1} \end{vmatrix} \frac{\varepsilon_i \varepsilon_{i+1} \cdots \varepsilon_{j-1}}{m(P_{j-1}P_j)} [V(\sigma_{P_{j-1}P_j})]$$

for each facet F of P.

We put

$$D(s,t) = \begin{vmatrix} b_s & \varepsilon_s^{-1} & 0 & \cdots & 0\\ \varepsilon_s^{-1} & b_{s+1} & \varepsilon_{s+1}^{-1} & \ddots & \vdots\\ 0 & \varepsilon_{s+1}^{-1} & \ddots & \ddots & 0\\ \vdots & \ddots & \ddots & b_{t-1} & \varepsilon_{t-1}^{-1}\\ 0 & \cdots & 0 & \varepsilon_{t-1}^{-1} & b_t \end{vmatrix}$$

for $2 < s \leq t < r$ and D(s,t) = 1 for s > t. Define $u \in (\mathbb{Q}^3)^*$ by $\langle u, v \rangle = 1, \langle u, v_{k_1} \rangle = 0, \langle u, v_{k_2} \rangle = 0$. By (3.1) and (3.2), we have

$$[V(\sigma_F)]^2 = -[V(\sigma_F)] \sum_{j=1}^r \langle u, v_{k_j} \rangle [V(\sigma_{F_{k_j}})] = -\sum_{j=3}^r \frac{\langle u, v_{k_j} \rangle}{m(P_{j-1}P_j)} [V(\sigma_{P_{j-1}P_j})].$$

Hence it suffices to show

(3.3)
$$\langle u, v_{k_j} \rangle = \sum_{i=2}^{j-1} a_i D(i+1, j-1) \varepsilon_i \varepsilon_{i+1} \cdots \varepsilon_{j-1}$$

for any $j = 3, \ldots, r$.

First we claim that

(3.4)
$$\varepsilon_{j-1}^{-1} v_{k_{j-1}} + \varepsilon_j^{-1} v_{k_{j+1}} = a_j v + b_j v_{k_j}$$

for any $j = 2, \ldots, r - 1$. By Cramer's rule, we have

$$v_{k_{j+1}} = \frac{\det(v_{k_{j+1}}, v_{k_j}, v_{k_{j-1}})}{\det(v, v_{k_j}, v_{k_{j-1}})}v + \frac{\det(v, v_{k_{j+1}}, v_{k_{j-1}})}{\det(v, v_{k_j}, v_{k_{j-1}})}v_{k_j} + \frac{\det(v, v_{k_j}, v_{k_{j+1}})}{\det(v, v_{k_j}, v_{k_{j-1}})}v_{k_{j-1}}$$
$$= \frac{\det(v_{k_{j+1}}, v_{k_j}, v_{k_{j-1}})}{\varepsilon_{j-1}}v + \frac{\det(v, v_{k_{j+1}}, v_{k_{j-1}})}{\varepsilon_{j-1}}v_{k_j} - \frac{\varepsilon_j}{\varepsilon_{j-1}}v_{k_{j-1}}.$$

So we have

(3.5)
$$\begin{aligned} \varepsilon_{j-1}^{-1} v_{k_{j-1}} + \varepsilon_{j}^{-1} v_{k_{j+1}} \\ &= \varepsilon_{j-1}^{-1} \varepsilon_{j}^{-1} \det(v_{k_{j+1}}, v_{k_{j}}, v_{k_{j-1}}) v + \varepsilon_{j-1}^{-1} \varepsilon_{j}^{-1} \det(v, v_{k_{j+1}}, v_{k_{j-1}}) v_{k_{j}}. \end{aligned}$$

Taking the inner product of both sides of (3.5) with $\overrightarrow{P_{j-1}Q_{j-1}}$ gives

$$\varepsilon_j^{-1} \langle \overrightarrow{P_{j-1}Q_{j-1}}, v_{k_{j+1}} \rangle = \varepsilon_{j-1}^{-1} \varepsilon_j^{-1} \det(v_{k_{j+1}}, v_{k_j}, v_{k_{j-1}}) \langle \overrightarrow{P_{j-1}Q_{j-1}}, v \rangle,$$

which means $a_j = \varepsilon_{j-1}^{-1} \varepsilon_j^{-1} \det(v_{k_{j+1}}, v_{k_j}, v_{k_{j-1}})$. Taking the inner product of both sides of (3.5) with $\overrightarrow{P_j P_{j+1}}$ gives

$$\varepsilon_{j-1}^{-1} \langle \overrightarrow{P_j P_{j+1}}, v_{k_{j-1}} \rangle = \varepsilon_{j-1}^{-1} \varepsilon_j^{-1} \det(v, v_{k_{j+1}}, v_{k_{j-1}}) \langle \overrightarrow{P_j P_{j+1}}, v_{k_j} \rangle,$$

which means $b_j = \varepsilon_{j-1}^{-1} \varepsilon_j^{-1} \det(v, v_{k_{j+1}}, v_{k_{j-1}})$. Thus (3.4) follows. We show (3.3) by induction on j. If j = 3, then both sides are $a_2 \varepsilon_2$. If j = 4, then both sides are $a_2b_3\varepsilon_2\varepsilon_3 + a_3\varepsilon_3$. Suppose $4 \le j \le r-1$. By (3.4) and the hypothesis of induction, we have

$$\langle u, v_{k_{j+1}} \rangle = \langle u, a_j \varepsilon_j v + b_j \varepsilon_j v_{k_j} - \varepsilon_{j-1}^{-1} \varepsilon_j v_{k_{j-1}} \rangle$$

$$= a_j \varepsilon_j + b_j \varepsilon_j \langle u, v_{k_j} \rangle - \varepsilon_{j-1}^{-1} \varepsilon_j \langle u, v_{k_{j-1}} \rangle$$

$$= a_j \varepsilon_j + b_j \varepsilon_j \sum_{i=2}^{j-1} a_i D(i+1, j-1) \varepsilon_i \varepsilon_{i+1} \cdots \varepsilon_{j-1}$$

$$- \varepsilon_{j-1}^{-1} \varepsilon_j \sum_{i=2}^{j-2} a_i D(i+1, j-2) \varepsilon_i \varepsilon_{i+1} \cdots \varepsilon_{j-2}.$$

On the other hand,

$$\sum_{i=2}^{j} a_i D(i+1,j)\varepsilon_i\varepsilon_{i+1}\cdots\varepsilon_j$$

= $a_j\varepsilon_j + a_{j-1}b_j\varepsilon_{j-1}\varepsilon_j + \sum_{i=2}^{j-2} a_i D(i+1,j)\varepsilon_i\varepsilon_{i+1}\cdots\varepsilon_j.$

Since

$$\sum_{i=2}^{j-2} a_i D(i+1,j)\varepsilon_i\varepsilon_{i+1}\cdots\varepsilon_j$$

=
$$\sum_{i=2}^{j-2} a_i (b_j D(i+1,j-1) - \varepsilon_{j-1}^{-2} D(i+1,j-2))\varepsilon_i\varepsilon_{i+1}\cdots\varepsilon_j$$

=
$$b_j\varepsilon_j \sum_{i=2}^{j-2} a_i D(i+1,j-1)\varepsilon_i\varepsilon_{i+1}\cdots\varepsilon_{j-1}$$

-
$$\varepsilon_{j-1}^{-1}\varepsilon_j \sum_{i=2}^{j-2} a_i D(i+1,j-2)\varepsilon_i\varepsilon_{i+1}\cdots\varepsilon_{j-2},$$

we have

$$\sum_{i=2}^{j} a_i D(i+1,j)\varepsilon_i\varepsilon_{i+1}\cdots\varepsilon_j$$

$$= a_j\varepsilon_j + a_{j-1}b_j\varepsilon_{j-1}\varepsilon_j + b_j\varepsilon_j\sum_{i=2}^{j-2} a_i D(i+1,j-1)\varepsilon_i\varepsilon_{i+1}\cdots\varepsilon_{j-1}$$

$$-\varepsilon_{j-1}^{-1}\varepsilon_j\sum_{i=2}^{j-2} a_i D(i+1,j-2)\varepsilon_i\varepsilon_{i+1}\cdots\varepsilon_{j-2}$$

$$= a_j\varepsilon_j + b_j\varepsilon_j\sum_{i=2}^{j-1} a_i D(i+1,j-1)\varepsilon_i\varepsilon_{i+1}\cdots\varepsilon_{j-1}$$

$$-\varepsilon_{j-1}^{-1}\varepsilon_j\sum_{i=2}^{j-2} a_i D(i+1,j-2)\varepsilon_i\varepsilon_{i+1}\cdots\varepsilon_{j-2}$$

$$= \langle u, v_{k_{i+1}} \rangle.$$

Thus (3.3) holds for j + 1. This completes the proof of Theorem 5.

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DEPARTMENT OF MATHEMATICS, GRADUATE SCHOOL OF SCIENCE, OSAKA CITY UNIVERSITY, 3-3-138 SUGIMOTO, SUMIYOSHI-KU, OSAKA 558-8585 JAPAN

E-mail address: d15san0w03@st.osaka-cu.ac.jp

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